

CAL C: LINE INTEGRALS & VECTOR FIELDS

Line Integrals and Vector Fields:

- Line integrals are used as a general form of integration over a curve C rather than an interval. The curve needs to be parameterized using a ray that traces location as a function of t :

$$\mathbf{r}(t) = g(t)\mathbf{i} + h(t)\mathbf{j} + k(t)\mathbf{k} \text{ for } a \leq t \leq b \text{ such that } f(x, y, z) = f(g(t), h(t), k(t))$$

- Knowing that $\left|\frac{ds}{dt}\right| = |\mathbf{v}(t)|$, a line integral is written:

$$\int_C f(x, y, z) ds = \int_a^b f(g(t), h(t), k(t)) \cdot |\mathbf{v}(t)| dt$$

- Line integrals can be used in vector fields to find work, flux, and more. A vector field is defined:

$$\mathbf{F}(x, y, z) = M(x, y, z)\mathbf{i} + N(x, y, z)\mathbf{j} + P(x, y, z)\mathbf{k}$$

- One notable vector field is the **gradient field**, defined by the gradient vector F of a scalar function f :

$$\nabla f = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}$$

- Knowing that the tangent vector is defined as $T = \frac{d\mathbf{r}}{ds}$, which defines the forward motion of the path, the line integral of a vector field \mathbf{F} over path $\mathbf{r}(t)$ can be written:

$$\int_C \mathbf{F} \cdot \mathbf{T} ds = \int_C \left(\mathbf{F} \cdot \frac{d\mathbf{r}}{ds} \right) ds = \int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \frac{d\mathbf{r}}{dt} dt$$

- It is known that this integral is equal to the work done by a force \mathbf{F} over a curve C from a to b as well as the flow of a fluid along the curve C .
- The flux of \mathbf{F} across the curve C is defined by the scalar component of the fluid's velocity in the direction of the curve's *outward facing normal vector* (while the tangential vector leads to flow **along** the curve, flux is concerned with flow **across** the curve).

$$\text{Flux} = \int_C \mathbf{F} \cdot \mathbf{n} ds = \int_C \mathbf{F} \cdot (\mathbf{T} \times \mathbf{k}) ds = \int_C \left(M \frac{dy}{ds} - N \frac{dx}{ds} \right) ds = \oint_C M dy - N dx$$